Area-perimeter generating functions of lattice walks: *q*-series and their asymptotics (A lattice model of vesicles attached to a skewed surface)

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Topic Outline

Motivation

- Vesicle Generating Function
- Singularity Diagram
- Scaling Function

Prom Lattice Walks to Basic Hypergeometric Series

- q-Deformed Algebraic Equations
- q-Difference Equations
- Basic Hypergeometric Series

3 Asymptotic Analysis

- Contour Integral Representation
- Saddle Point Analysis
- Uniform Asymptotics

Outlook

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Vesicle Generating Functio Singularity Diagram Scaling Function

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Vesicle Generating Function Singularity Diagram Scaling Function

Vesicle Generating Function

- 3-dim vesicle (bubble) with surface and volume
- 2-dim lattice model: polygons on the square lattice



 $c_{m,n}$ number of polygons with area m and perimeter 2n

Vesicle Generating Function Singularity Diagram Scaling Function

Vesicle Generating Function

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 $c_{m,n}$ number of polygons with area m and perimeter 2n

$$G(x,q) = \sum_{n,m} c_{m,n} x^n q^m$$
 generating function

Wanted:

- an explicit formula for G(x,q)
- singularity structure, e.g. $q_c(x)$

Vesicle Generating Function Singularity Diagram Scaling Function

Singularity Diagram

Folklore: universal behaviour near a "critical point"



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Vesicle Generating Function Singularity Diagram Scaling Function

Singularity Diagram

Folklore: universal behaviour near a "critical point"



• scaling function f with crossover exponent ϕ :

$$G^{sing}(x,q) \sim (1-q)^{-\gamma_t} f\left([1-q]^{-\phi}[x_t-x]
ight)$$

as $q \to 1$ and $x \to x_t$ with $z = [1-q]^{-\phi}[x_t-x]$ fixed

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Vesicle Generating Function Singularity Diagram Scaling Function

Scaling Function

Surprisingly often f(z) = -Ai'(z)/Ai(z)

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- Square lattice vesicle generating function
 - Enumeration of *c*_{*m*,*n*}, numerical analysis of moments (Richard, Guttmann, Jensen)

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- Staircase polygons (skew-Ferrer diagrams)
 - Rigorous derivation (Prellberg)

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 - Probabilistic analysis (Louchard)

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- Area statistics of outer boundary of random loops
 - Monte-Carlo simulation (Richard)

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 - Monte-Carlo simulation (Richard)
- q-Analogue of the Painlevé II equation (Witte)

-Deformed Algebraic Equations -Difference Equations asic Hypergeometric Series

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7-Deformed Algebraic Equations 7-Difference Equations Basic Hypergeometric Series

Example 1: Dyck Paths



2n = 14 steps enclosing an area of size m = 9

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7-Deformed Algebraic Equations 7-Difference Equations Basic Hypergeometric Series

Example 1: Dyck Paths



2n = 14 steps enclosing an area of size m = 9

$$G(t,q)=\sum_{m,n}c_{m,n}t^nq^m$$

t counts pairs of up/down steps, q counts enclosed area

q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 1: Dyck Paths

• A functional equation



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q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 1: Dyck Paths

A functional equation



• C(t) = G(t, 1) satisfies $C(t) = 1 + tC(t)^2$

$$C(t) = \frac{1 - \sqrt{1 - 4t}}{2t} = \sum_{n=0}^{\infty} \frac{t^n}{n + 1} \binom{2n}{n}$$

Generating function of Catalan numbers

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q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 2: A Pair of Directed Walks



Two directed walks not allowed to cross

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q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 2: A Pair of Directed Walks



Two directed walks not allowed to cross

$$G(x, y, q) = \sum_{m, n_x, n_y} c_{m, n_x, n_y} x^{n_x} y^{n_y} q^m$$

x and y count pairs of east and north steps, q counts enclosed area

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q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 2: A Pair of Directed Walks

• A functional equation



G(x, y, q) = 1 + yG(qx, y, q) + xG(x, y, q) + yG(qx, y, q)xG(x, y, q)

q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 2: A Pair of Directed Walks

• A functional equation



G(x, y, q) = 1 + yG(qx, y, q) + xG(x, y, q) + yG(qx, y, q)xG(x, y, q)

• G(t, t, 1) = 1 + tC(t) Catalan generating function

q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 3: Partially Directed Walks Above y = x



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Example 3: Partially Directed Walks Above y = x



•
$$G(x, y, 1) = C\left(\frac{xy}{1-y^2}\right)$$
 Catalan generating function

q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Summary of the Examples

Different *q*-deformations of Catalan-type generating functions:

Dyck paths

$$G(t) = 1 + tG(t)G(qt)$$

Pair of directed walks

$$G(x) = (1 + xG(x))(1 + yG(qx))$$

• Partially directed walks above the diagonal

$$G(x) = 1 + xyG(x)G(qx) + y^{2}(G(qx) - 1)$$

q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 1: Solving G(t) = 1 + tG(t)G(qt)

An aside:

• G(t) admits a nice continued fraction expansion



• Connections with orthogonal polynomials, combinatorics of weighted lattice paths, ...

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q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 1: Solving G(t) = 1 + tG(t)G(qt)

An aside:

• G(t) admits a nice continued fraction expansion



- Connections with orthogonal polynomials, combinatorics of weighted lattice paths, ...
- However, useless for finer asymptotic analysis of $q \rightarrow 1$.

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q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 1: Solving G(t) = 1 + tG(t)G(qt)

Better:

• Linearise the functional equation using

$$G(t) = rac{H(qt)}{H(t)}$$

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q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 1: Solving G(t) = 1 + tG(t)G(qt)

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• Obtain a linear q-difference equation

$$H(qt) = H(t) + tH(q^2t)$$

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$$H(qt) = H(t) + tH(q^2t)$$

• Explicit solution

$$H(t) = \sum_{n=0}^{\infty} \frac{q^{n^2 - n} (-t)^n}{(q;q)_n} = {}_0\phi_1(-;0;q,-t)$$

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 $[_0\phi_1(-;0;q,-qt) \text{ a } q$ -Airy function (Ismail)]

q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 2: Solving G(x) = (1 + xG(x))(1 + yG(qx))

Better:

• Linearise the functional equation using

$$G(x) = \frac{1}{x} \left(\frac{H(qx)}{H(x)} - 1 \right)$$

• Obtain a linear q-difference equation

$$q(H(qx) - H(x)) = qxH(qx) + y(H(q^2x) - H(qx))$$

Explicit solution

$$H(t) = \sum_{n=0}^{\infty} \frac{q^{\binom{n}{2}}(-x)^n}{(y;q)_n(q;q)_n} = {}_1\phi_1(0;y;q,x)$$

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q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Example 3: $G(x) = 1 + xyG(x)G(qx) + y^2(G(qx) - 1)$

Better:

• Linearise the functional equation using

$$G(x) = rac{y}{x} \left(rac{H(qx)}{H(x)} - 1
ight)$$

• Obtain a linear q-difference equation

$$q(H(qx) - H(x)) = qx(1/y - y)H(qx) + y^{2}(H(q^{2}x) - H(qx))$$

Explicit solution

$$H(t) = \sum_{n=0}^{\infty} \frac{(-x(1-y^2)/y)^n}{(y^2; q)_n(q; q)_n} = {}_2\phi_1(0, 0; y^2; q, -x(1-y^2)/y)$$

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q-Deformed Algebraic Equations *q*-Difference Equations Basic Hypergeometric Series

Summary:

Different *q*-deformations of Catalan-type generating functions:

• Dyck paths

$$G(t,q) = rac{{_0}\phi_1(-;0;q,-qt)}{{_0}\phi_1(-;0;q,-t)}$$

Pair of directed walks

$$G(x, y, q) = \frac{1}{x} \left(\frac{{}_{1}\phi_{1}(0; y; q, qx)}{{}_{1}\phi_{1}(0; y; q, x)} - 1 \right)$$

• Partially directed walks above the diagonal

$$G(x, y, q) = \frac{y}{x} \left(\frac{2\phi_1(0, 0; y^2; q, qx(y - 1/y))}{2\phi_1(0, 0; y^2; q, x(y - 1/y))} - 1 \right)$$

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Contour Integral Representation Saddle Point Analysis Jniform Asymptotics

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

A Puzzle

• The full generating function is a quotient of *q*-series, e.g.

$$G(t,q) = \frac{\sum_{n=0}^{\infty} \frac{q^{n^2}(-t)^n}{(q;q)_n}}{\sum_{n=0}^{\infty} \frac{q^{n^2-n}(-t)^n}{(q;q)_n}}$$

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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• However, for q = 1 we have a simple algebraic generating function

$$G(t,1)=\frac{1-\sqrt{1-4t}}{2t}$$

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

A Puzzle

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$$G(t,1)=\frac{1-\sqrt{1-4t}}{2t}$$

How can one understand the limit $q \rightarrow 1$?

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

A Standard Trick For Evaluating Alternating Series

• Write an alternating series as a contour integral

$$\sum_{n=0}^{\infty} (-x)^n c_n = \frac{1}{2\pi i} \oint_{\mathcal{C}} x^s c(s) \frac{\pi}{\sin(\pi s)} ds$$

C runs counterclockwise around the zeros of $sin(\pi s)$

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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C runs counterclockwise around the zeros of $sin(\pi s)$

• For example,

$$\exp(-x) = \sum_{n=0}^{\infty} \frac{(-x)^n}{n!} = \frac{1}{2\pi i} \int_{-c-i\infty}^{-c+i\infty} x^s \Gamma(-s) ds$$

where c > 0 (here, we have used $\Gamma(s)\Gamma(1-s) = \pi/\sin(\pi s)$)

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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Find suitable q-version for this trick

Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

Contour Integral Representation

Use that

Res
$$[(z;q)_{\infty}^{-1}; z = q^{-n}] = -\frac{(-1)^n q^{\binom{n}{2}}}{(q;q)_n (q;q)_{\infty}}$$
 $n = 0, 1, 2, ...$

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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 $n = 0, 1, 2, ...$

to prove that

Lemma

For complex t with $|\arg(x)| < \pi,$ non-negative integer n, and 0 < q < 1 we have for $0 < \rho < 1$

$$\sum_{n=0}^{\infty} \frac{q^{n^2 - n} (-t)^n}{(q;q)_n} = \frac{(q;q)_{\infty}}{2\pi i} \int_{\rho - i\infty}^{\rho + i\infty} \frac{z^{\frac{1}{2}\log_q z - \log_q t}}{(z;q)_{\infty}} \sqrt{z} \, dz$$

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

Some Asymptotics

Approximate
$$\log(z; q)_{\infty} \sim \frac{1}{\log q} \operatorname{Li}_2(z) + \frac{1}{2} \log(1-z)$$
 to get

Lemma

For
$$0 < t < 1$$
 and with $\varepsilon = -\log q$

$$\sum_{n=0}^{\infty} \frac{q^{n^2 - n} (-t)^n}{(q;q)_n} = \frac{(q;q)_{\infty}}{2\pi i} \int_{\rho - i\infty}^{\rho + i\infty} e^{\frac{1}{\varepsilon} \left[-\frac{1}{2} (\log z)^2 + \log(z) \log(t) + \operatorname{Li}_2(z) \right]} \sqrt{\frac{z}{1 - z}} \, dz \left[1 + O(\varepsilon) \right]$$

where $t < \rho < 1$

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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where $t < \rho < 1$

We find a Laplace-type integral, where the saddles are given by

$$0 = \frac{d}{dz} \left[-\frac{1}{2} (\log z)^2 + \log(z) \log(t) + \operatorname{Li}_2(z) \right]$$

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

Saddle Point Analysis

• The asymptotics of

$$\int_{\mathcal{C}} e^{\frac{1}{\varepsilon}g(z)} f(z) dz$$

is dominated by the saddles with g'(z) = 0.

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

Saddle Point Analysis

• The asymptotics of

$$\int_{\mathcal{C}} e^{\frac{1}{\varepsilon}g(z)}f(z)dz$$

is dominated by the saddles with g'(z) = 0.

• For $g(z) = -\frac{1}{2}(\log z)^2 + \log(z)\log(t) + \text{Li}_2(z)$ we find two saddles given by the zeros of

$$z(1-z) = t \quad \Rightarrow \quad z = \frac{1}{2} \pm \frac{1}{2}\sqrt{1-4t}$$

Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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As t approaches $t_t = 1/4$, the saddles coalesce

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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As t approaches $t_t = 1/4$, the saddles coalesce

Standard procedure: reparametrise locally by a cubic and compute a uniform asymptotic expansion (involving Airy functions)...

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

Saddle Point Summary:

Saddle Point coalescence occurs in all three cases:

• Dyck paths,
$$_{0}\phi_{1}(-; 0; q, -t)$$
:

$$g(z) = -\frac{1}{2}(\log z)^2 + \log(z)\log(t) + \operatorname{Li}_2(z) \quad \Rightarrow \quad (z-1)z + t = 0$$

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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Saddle Point coalescence occurs in all three cases:

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• Pair of directed walks, $_1\phi_1(0; y; q, x)$:

$$g(z) = -\text{Li}_2(y/z) + \log(z)\log(x) + \text{Li}_2(z) \quad \Rightarrow \quad (z-1)(z-y) + zx = 0$$

Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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• Part. directed walks above the diagonal, $_2\phi_1(0,0;y^2;q,x(y-1/y))$:

$$g(z) = \dots$$
 \Rightarrow $(z-1)(z-y^2) + z^2 x(1/y-y) = 0$

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

Uniform Asymptotics

Theorem

Let 0 < t < 1 and $\varepsilon = -\log q$. Then, as $\varepsilon \to 0^+$,

$$G(t,q) \sim \frac{1}{2} \left(1 - \sqrt{1-4t} \left[-\frac{\operatorname{Ai}'(\alpha \varepsilon^{-2/3})}{\alpha^{1/2} \varepsilon^{-1/3} \operatorname{Ai}(\alpha \varepsilon^{-2/3})} \right] \right)$$

where $\alpha = \alpha(t)$ is an explicitly given function of t. In particular,

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

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Some remarks:

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Contour Integral Representation Saddle Point Analysis Uniform Asymptotics

Uniform Asymptotics

Theorem

Let
$$0 < t < 1$$
 and $\varepsilon = -\log q$. Then, as $\varepsilon \to 0^+$,

$$G(t,q) \sim \frac{1}{2} \left(1 - \sqrt{1-4t} \left[-\frac{\operatorname{Ai}'(\alpha \varepsilon^{-2/3})}{\alpha^{1/2} \varepsilon^{-1/3} \operatorname{Ai}(\alpha \varepsilon^{-2/3})} \right] \right)$$

where $\alpha = \alpha(t)$ is an explicitly given function of t. In particular,

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The result is completely analogous for the other examples.

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Outline

Motivation

- Vesicle Generating Function
- Singularity Diagram
- Scaling Function

2 From Lattice Walks to Basic Hypergeometric Series

- q-Deformed Algebraic Equations
- q-Difference Equations
- Basic Hypergeometric Series

3 Asymptotic Analysis

- Contour Integral Representation
- Saddle Point Analysis
- Uniform Asymptotics

4 Outlook

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So far:

- simple *q*-algebraic equation
- simple *q*-series solution
- contour integral
- saddle-point analysis

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The End